

GENERAL SPECIFICATIONS

ELECTRICAL

Power Supply Requirements

Voltage¹

-4 version +12 to +48 VDC
 -7 version +24 to +75 VDC

¹Includes Motor Back EMF, Ripple and Hi Line.

Current²

-4 version 2 Amps typical
 -7 version 3 Amps typical

²Actual requirements depend on application and programmable current settings.

RECOMMENDED SUPPLY: ISP200 (-4/-7)

Motor Drive

Motor Type 2/4 phase bipolar stepper
 Motor Current (software programmable)
 -4 version to 4 Amps peak
 -7 version to 7 Amps peak
 Resolution
 Number of settings 14
 Steps per Revolution
 (1.8° Motor) 400, 800, 1000, 1600, 2000,
 3200, 5000, 6400, 10000,
 12800, 25000, 25600,
 50000, 51200

General Purpose I/O

Number of I/O 6
 Input Voltage +5 to +24 VDC
 Output Current Sink 350 mA
 Input Filter Range 215Hz to 21.5kHz (programmable)
 Pull-ups 7.5 kOhm individually switchable
 Pull-up Voltage +5 VDC on-board or externally up
 to +24 VDC
 Protection Over Temp, Short Circuit,
 Inductive Clamp
 Isolated Ground Common to 6 I/O

COMMUNICATION

Asynchronous

Interface Type COMM 1: RS-232
 COMM 2: RS-485
 Number of Bits/Character 8
 Parity none
 Handshake none
 Baud Rate 4.8 to 38.4kbps selectable
 Error Checking 16 bit check sum (binary mode)
 ASCII Text or Binary Communication Modes

CAN

CAN Communications replaces Asynchronous Communications in Base System (uses COMM 1 internally)

CAN compliance Version 2.0B Active

2 receive message frames
 1 transmit frame

Isolated Ground Common to COMM1 and COMM2

MOTION

Counters

Type Position, Encoder1, Encoder2: 32 Bits
 Edge Rate (Max) 5 MHz

Electronic Gearing[†]

External Clock In
 Range* -1 to 1
 Resolution 32 Bits
 Secondary Clock Out
 Range* -2 to 2
 Resolution 16 Bits

[†] Requires Differential I/O Expansion Module.

* Adjusting the microstep resolution of the driver can increase the range.

Velocity

Range ±5,000,000 steps/sec
 Resolution 0.005 steps/sec
 Update Period 25.6 Microseconds

Acceleration/Deceleration

Range ±1,530,000,000 steps/sec²
 Resolution 0.711 steps/sec²
 Types Linear, triangle s-curve, parabolic,
 sinusoidal s-curve, user defined

SOFTWARE

User Program Space 8175 Bytes
 Number of User Definable
 Labels, Variables and Flags ... 291
 Program and Data Storage ... Flash
 Math, Logic and Conditional
 Functions 32 Bit Floating Point Math IEEE
 Format-Add, Subtract, Multiply,
 Divide, Sine, Cosine, Tangent, Arc
 Sine, Arc Cosine, Arc Tangent,
 AND, OR, XOR, NOT, Less Than,
 Greater Than, Equal, Square
 Root, Absolute, Integer Part,
 Fractional Part
 Acceleration & Deceleration ... Separate Variables and Flags
 4 Pre-Defined Types and
 1 User Defined
 Limit Switch Definable: Deceleration and Type
 Isolated I/O Line Software Selectable as
 Dedicated or General Purpose
 Predefined I/O Functions 25 (Limit, Home, etc.)
 Program Trip Functions 13 - 4 I/O Input Trips,
 4 Timer Trips, 4 Position Trips,
 1 Velocity Trip
 User Programs 2 Executed Simultaneously -
 1 Foreground, 1 Background
 Party Mode Names 62
 Communication Modes 2 - ASCII, Binary
 Mechanical Compensation Backlash
 Encoder Functions Stall Detection and
 Position Maintenance

ENVIRONMENTAL

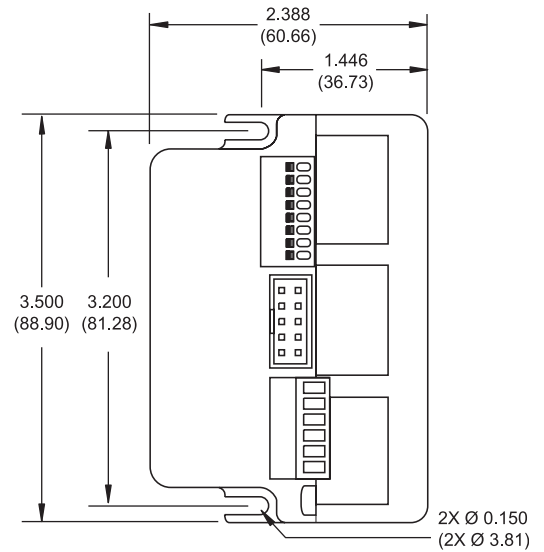
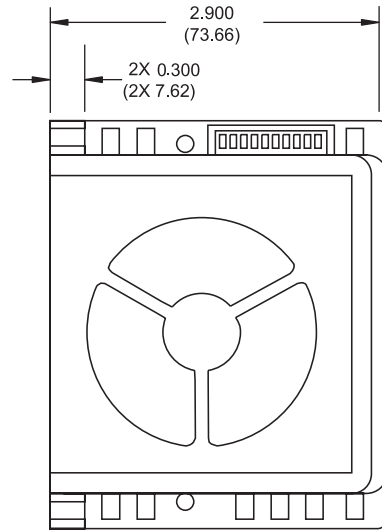
Ambient Operating Temp 0 to 50° C*
 Storage Temperature -20 to 70° C
 Humidity 0 to 90% non-condensing
 * Can be duty cycle dependent.

MECHANICAL

Dimensions (see Mechanical Specs)
 # of Expansion Modules up to 3
 Cooling Built-in fan
 Mounting 2-#6 (or M3.5) machine screws
 Mounting Screw Torque 5.0 to 7.0 lb-in

MECHANICAL SPECIFICATIONS

Dimensions in Inches (mm)



CONNECTORS

Power and Motor

6 position pluggable terminal block connector.

PIN	SIGNAL NAME	FUNCTION
1	Phase A	Motor Connections
2	Phase /A	
3	Phase B	
4	Phase /B	
5	+V	Input Power
6	Ground	

Power and Motor Connections

Communication –

Dual COMM Version

7 position pluggable terminal block connector or optional 10 pin pin-header.

PIN	CONNECTOR OPTION	
	TERMINAL BLOCK	PIN HEADER
1	232RX	NO CONNECT
2	232TX	232TX
3	485RX-	232RX
4	485RX+	NO CONNECT
5	485TX-	C GROUND
6	C GROUND	485RX+
7	485TX+	485RX-
8		485TX-
9		485TX+
10		C GROUND

Asynchronous Communications Connections

CAN Version

7 position pluggable terminal block connector or optional 10 pin pin-header.

PIN	CONNECTOR OPTION	
	TERMINAL BLOCK	PIN HEADER
1	V- (C Ground)	NO CONNECT
2	CAN_L	CAN_L
3	SHIELD	V- (C Ground)
4	CAN_H	SHIELD
5	NC (reserved for V+)	SHIELD
6	/CONFIG	NO CONNECT
7	NO CONNECT	CAN_H
8		NO CONNECT
9		NC (reserved for V+)
10		/CONFIG

CAN Comm1 Communications Connections (Comm2 Available with Expansion Modules)

General Purpose I/O

8 position pluggable terminal block connector or optional 10 pin pin-header.

PIN	CONNECTOR OPTION	
	TERMINAL BLOCK	PIN HEADER
1	VPULLUP	I/O 21
2	I/O 21	I/O 22
3	I/O 22	VPULLUP
4	I/O 23	I/O 23
5	I/O 24	FAULT INPUT +
6	I/O 25	I/O 24
7	I/O 26	FAULT INPUT -
8	I/O GROUND	I/O 25
9		I/O GROUND
10		I/O 26

General Purpose I/O Connections

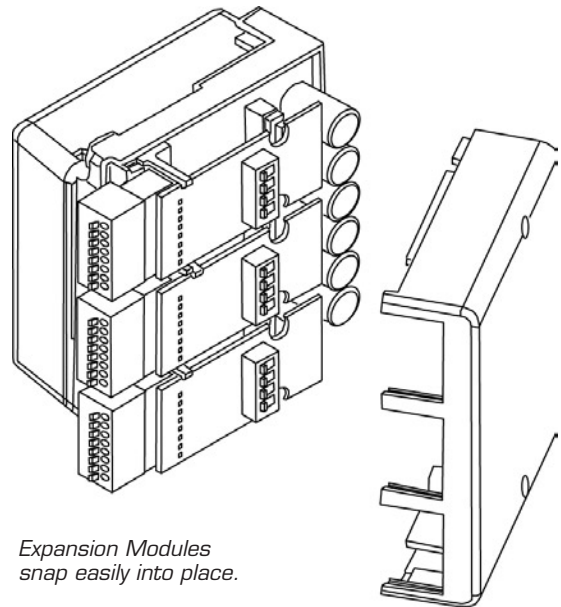
SWITCHES

SWITCH	SIGNAL NAME	FUNCTION
1-6	I/O 21-26	Pull-up on/off Switches for I/O Lines 21-26
7-9	Address 2-0	Multi-drop Communication Address (also settable by software)
10	Upgrade	Firmware Upgrade

EXPANSION MODULES

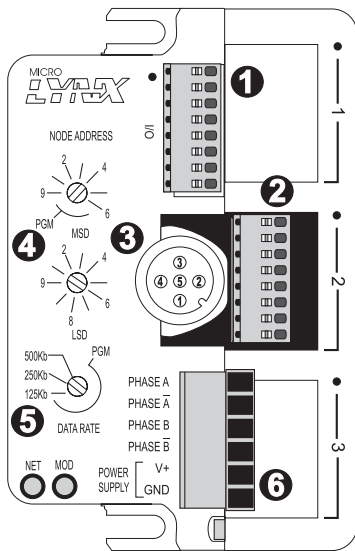
Up to three expansion modules can be added. Modules can be combined to fill the three expansion slots. Module types are limited to 2 Analog Input/Joystick Modules, 2 Analog Output Modules, 1 Twelve Channel I/O Module, up to 2 High-Speed Differential I/O Modules, and up to 3 General Purpose I/O Modules per system.

By simply removing two screws on the side cover, expansion modules can be added, removed or reconfigured. No additional hardware is required. Modules snap easily into place, making even field change quick and easy.



Expansion Modules snap easily into place.

DEVICENET MicroLYNX



- ❶ I/O Connector
- ❷ Encoder Connector*
- ❸ DeviceNet Connector
- ❹ Address Select Switches
- ❺ Data Rate Select Switch
- ❻ Motor/Power

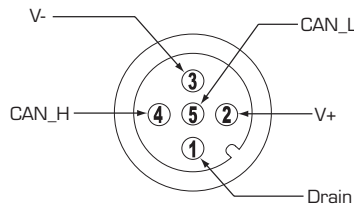
* High Speed Differential I/O Board Optional for Encoder Functions. Board must be placed in Expansion Slot #2. Note that the High Speed Differential I/O Expansion is the ONLY Expansion Module available for the DeviceNet MicroLYNX.

The DeviceNet MicroLYNX is specifically designed to conform with ODVA Volume II, Release 2.0 Errata 3 as a Position Controller (Device Type 16).

- Node Address MSD and LSD switch-selectable on front panel.
- Data Rate switch-selectable on front panel.
- Conforms to the Predefined Master/Slave Connection Set as a group 2 Slave.
- Supports Poll IO and Explicit Messaging.
- Included GUI to aid in configuration and EDS file.
- No support for UCMM.

Communication

5 Pin DeviceNet Micro, Male



DeviceNet I/O

8 position pluggable terminal block connector or optional 10 pin pin-header.

PIN	CONNECTOR OPTION	
	TERMINAL BLOCK	PIN HEADER
1	VPULLUP	Home Input
2	Home Input	CW Limit Input
3	CW Limit Input	VPULLUP
4	CWW Limit Input	CWW Limit Input
5	Fault Input	NC
6	Brake Output	Fault Input
7	General Purpose	NC
8	I/O Ground	Brake Output
9		I/O Ground
10		General Purpose

DeviceNET I/O Connections

ORDER INFORMATION

Standard Product Shown in ***Bold Italics***. Longer Lead Times May Apply to Other Versions.

Note: Terminal Block Mating Connector Supplied.

Pin Header Mating Connector **Not Supplied**, order information at www.imshome.com/quick.html.

MICROLYNX CONTROL SYSTEMS

TYPE	DESCRIPTION	CONNECTOR TYPE		PART NUMBER	
		COMMUNICATION	I/O	4 AMP DRIVER	7 AMP DRIVER
Control System with Asynchronous Communication	[6] +5 to +24 VDC Isolated I/O, RS-232 and RS-485 Communication, 4 or 7 Amp Motor Drive	Pin Header**	Terminal Block	<i>MX-CS100-401</i>	<i>MX-CS100-701</i>
		Terminal Block	Terminal Block	MX-CS101-401	MX-CS101-701
		Pin Header**	Pin Header	MX-CS102-401	MX-CS102-701
		Terminal Block	Pin Header	MX-CS103-401	MX-CS103-701
Control System with CAN Communication	[6] +5 to +24 VDC Isolated I/O, CAN Communication, 4 or 7 Amp Motor Drive	Pin Header	Terminal Block	MX-CS200-401	MX-CS200-701
		Terminal Block	Terminal Block	MX-CS201-401	MX-CS201-701
		Pin Header	Pin Header	MX-CS202-401	MX-CS202-701
		Terminal Block	Pin Header	MX-CS203-401	MX-CS203-701
Control System with DeviceNet Communication	[6] +5 to +24 VDC Isolated I/O, DeviceNet Communication, 4 or 7 Amp Motor Drive	DeviceNet Micro, Male	Terminal Block	MX-CS300-401	MX-CS300-701
			Pin Header	MX-CS302-401	MX-CS302-701

**Communication cable accessory recommended with first order.

EXPANSION MODULES

TYPE (max # per system)	DESCRIPTION	PART NUMBER	
		TERMINAL BLOCK	PIN HEADER
Isolated Digital I/O Module (3)	[6] +5 to +24 VDC General Purpose Isolated Digital I/O	<i>MX-DI100-000</i>	MX-DI200-000
High-Speed Differential I/O Module (2)	[3] High-Speed Differential (or Single Ended) Lines for General Purpose I/O, Encoder Feedback, Electronic Gearing, or Driving an Additional Axis Sequentially	<i>MX-DD100-000</i>	MX-DD200-000
Analog Input/Joystick Module (2)	[2] Channels of 0 to +5 VDC 12 Bit Resolution Analog Input or Single Axis Joystick	<i>MX-AJ100-000</i>	MX-AJ200-000
Analog Output Module (2)	[2] Channels (Up to 4 total) of 0 to +5 VDC 12 Bit Resolution Analog Output	<i>MX-DA100-000</i>	MX-DA200-000
RS-232 Communication Module (1)	RS-232 Port 2 Communication Module used <i>only</i> with CAN Based Control System – <i>cannot combine with RS-485 Module</i>	MX-CM102-000	<i>MX-CM202-000</i>
RS-485 Communication Module (1)	RS-485 Port 2 Communication Module used <i>only</i> with CAN Based Control System – <i>cannot combine with RS-232 Module</i>	<i>MX-CM104-000</i>	MX-CM204-000
12 Channel I/O Module (1)	General Purpose I/O Module with Twelve +5 to +24 VDC Isolated Digital I/O	Not Available	<i>MX-DI400-000</i> PIN & RECEPTACLE MX-DI401-000†

†Refer to 12 Channel I/O page for details.

ACCESSORIES

TYPE	DESCRIPTION	PART NUMBER
Human Machine Interface (HMI)	A Programmable User Interface with 20 Character by 4 Line Display, 6 Function Keys, Numeric Keypad	<i>LX-HI100-000</i>
Communication Cable	10 Pin Pin-Receptacle to 9 Pin Sub D Provides Easy Connection for RS-232 Communication	<i>MX-CC100-000</i>
Communication Cable (For Party Line)	[2] 10 Pin Pin-Receptacle to 9 Pin Sub D (For Party Line Communication with Two MicroLYNX) Provides Easy Connection for RS-232 Communication to First MicroLYNX and RS-485 Communication from First to Second MicroLYNX	<i>MX-CC200-000</i>
Operating Manual	Operating Instruction Manual for MicroLYNX Systems - Paper Version*	<i>LX-OM200-000</i>
6 Pin Terminal Block	[6] Pin Screw-Type Terminal Block – Motor and Power	<i>MX-CN006</i>
7 Pin Terminal Block	[7] Pin Spring Clamp Terminal Block 0.1" Center – MicroLYNX Communications	<i>MX-CN007</i>
8 Pin Terminal Block	[8] Pin Spring Clamp Terminal Block 0.1" Center, MicroLYNX I/O and Expansion Modules	<i>MX-CN008</i>
CAN Dongle	Communication Cable for MicroLYNX CAN Version	MX-CC500-000
DeviceNet Programmer	Cable for use in Upgrading MicroLYNX DeviceNet Firmware	MX-CC600-000

*Manual on CD provided with system shipment.