

Description	Power Range
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The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a single RS-232/RS-485 interface used for drive configuration and setup. Drive commissioning is accomplished using DriveWare® 7, available for download at [www.a-m-c.com](http://www.a-m-c.com).

All drive and motor parameters are stored in non-volatile memory.

Peak Current	20 A (14.1 A <sub>RMS</sub> )
Continuous Current	10 A (10 A <sub>RMS</sub> )
Supply Voltage	20 - 80 VDC



### Features

- |  |   |
|--|---|
| <ul style="list-style-type: none"> <li>▲ Four Quadrant Regenerative Operation</li> <li>▲ Space Vector Modulation (SVM) Technology</li> <li>▲ Fully Digital State-of-the-art Design</li> <li>▲ Programmable Gain Settings</li> <li>▲ Fully Configurable Current, Voltage, Velocity and Position Limits</li> </ul> | <ul style="list-style-type: none"> <li>▲ PIDF Velocity Loop</li> <li>▲ PID + FF Position Loop</li> <li>▲ Compact Size, High Power Density</li> <li>▲ 16-bit Analog to Digital Hardware</li> <li>▲ On-the-Fly Mode Switching</li> <li>▲ On-the-Fly Gain Set Switching</li> </ul> |
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#### MODES OF OPERATION

- Current
- Position
- Velocity
- Hall Velocity

#### COMMAND SOURCE

- ±10 V Analog
- 5V Step and Direction
- Encoder Following
- Over the Network
- Indexing
- Jogging

#### FEEDBACK SUPPORTED

- Halls
- Incremental Encoder
- ±10 VDC Position
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

#### INPUTS/OUTPUTS

- 3 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 2 Programmable Analog Outputs (10-bit Resolution)
- 2 Programmable Digital Inputs (Differential)
- 4 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

#### COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS





**PIN FUNCTIONS**

COMM - RS232/RS485 Communication Connector			
Pin	Name	Description / Notes	I/O
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	O
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I
4	RESERVED	Reserved	-
5	ISO GND	Isolated Signal Ground	IGND
6	RS485 TX+	Transmit Line (RS-485)	O
7	RESERVED	Reserved	-
8	RS485 RX+	Receive Line (RS-485)	I
9	RESERVED	Reserved	-

FEEDBACK - Feedback Connector			
Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

I/O - Signal Connector			
Pin	Name	Description / Notes	I/O
1	PDO-1	Programmable Digital Output	O
2	SGN GND	Signal Ground	SGND
3	PDO-2	Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	O
8	PAO-2	Programmable Analog Output (10-bit Resolution)	O
9	PDI-6 - (DIR- / AUX ENC B-)	Programmable Digital Input or Direction- or Auxiliary Encoder (For Differential Signals Only)	I
10	PDO-3		O
11	PDI-1	Programmable Digital Input	I
12	PDI-2	Programmable Digital Input	I
13	PDI-3	Programmable Digital Input	I
14	PDO-4	Programmable Digital Output	O
15	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
16	SGN GND	Signal Ground	SGND
17	PDI-5 + (STEP+ / AUX ENC A+)	Programmable Digital Input or Step+ or Auxiliary Encoder	I
18	PDI-6 + (DIR+ / AUX ENC B+)	Programmable Digital Input or Direction+ or Auxiliary Encoder	I
19	PDI-4	Programmable Digital Input	I
20	ENC A+ OUT	Buffered Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Buffered Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Buffered Encoder Index Output	O
25	ENC I- OUT	Buffered Encoder Index Output	O
26	PDI-5 - (STEP- / AUX ENC A-)	Programmable Digital Input or Step- or Auxiliary Encoder (For Differential Signals Only)	I

POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	MOTOR A	Motor Phase A	O
2	MOTOR B	Motor Phase B	O
3	MOTOR C	Motor Phase C	O
4	HIGH VOLTAGE	DC Power Input	I
5	PWR GND	Power Ground (Common With Signal Ground)	PGND
6	LOGIC PWR	Logic Supply Input	I

## HARDWARE SETTINGS

### Switch Functions

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary RS-485 drive address. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive RS-485 baud rate setting. Does not affect RS-232 settings.	1	0

#### Additional Details

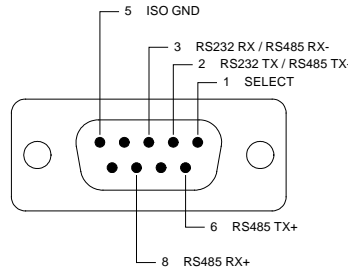
The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Baud Rate (kbps)	Value For Bit Rate Setting
Load from non-volatile memory	0
9.6	1
38.4	2
115.2	3

**MECHANICAL INFORMATION**

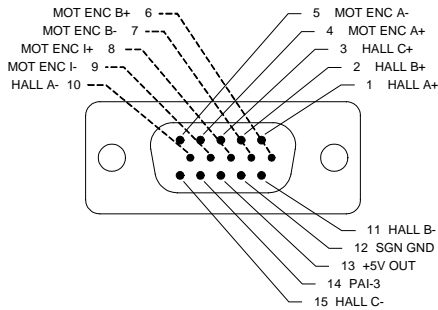
**COMM - RS232/RS485 Communication Connector**

Connector Information		9-pin, female D-sub
Mating Connector	Details	TYCO: Plug P/N 205204-4; Housing P/N 5748677-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)
	Included with Drive	No



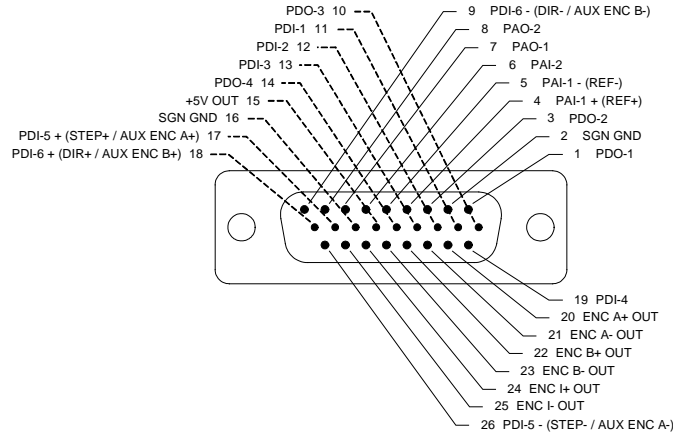
**FEEDBACK - Feedback Connector**

Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



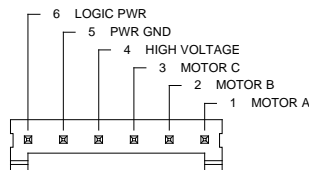
**I/O - Signal Connector**

Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No

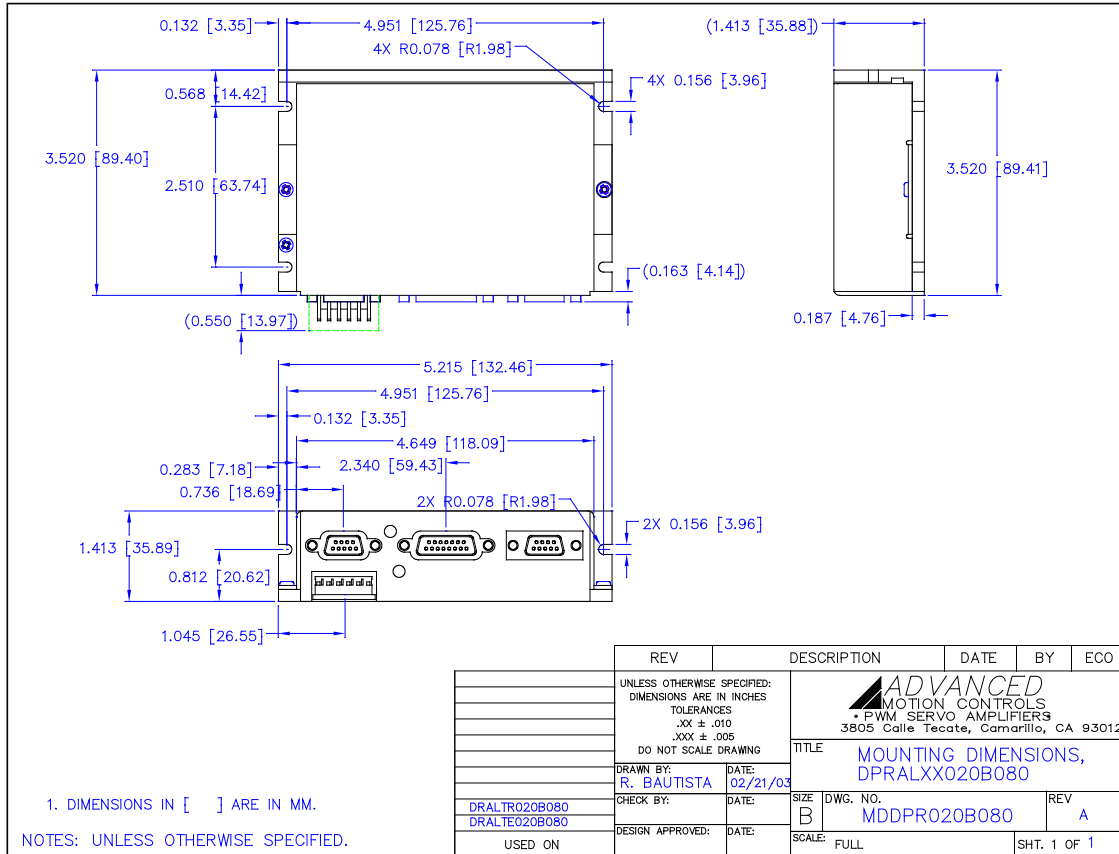


**POWER - Power Connector**

Connector Information		6-pin, 3.96 mm spaced, friction lock header
Mating Connector	Details	AMP: Plug P/N 770849-6; Terminals P/N 770522-1 (loose) or 770476-1 (strip)
	Included with Drive	Yes

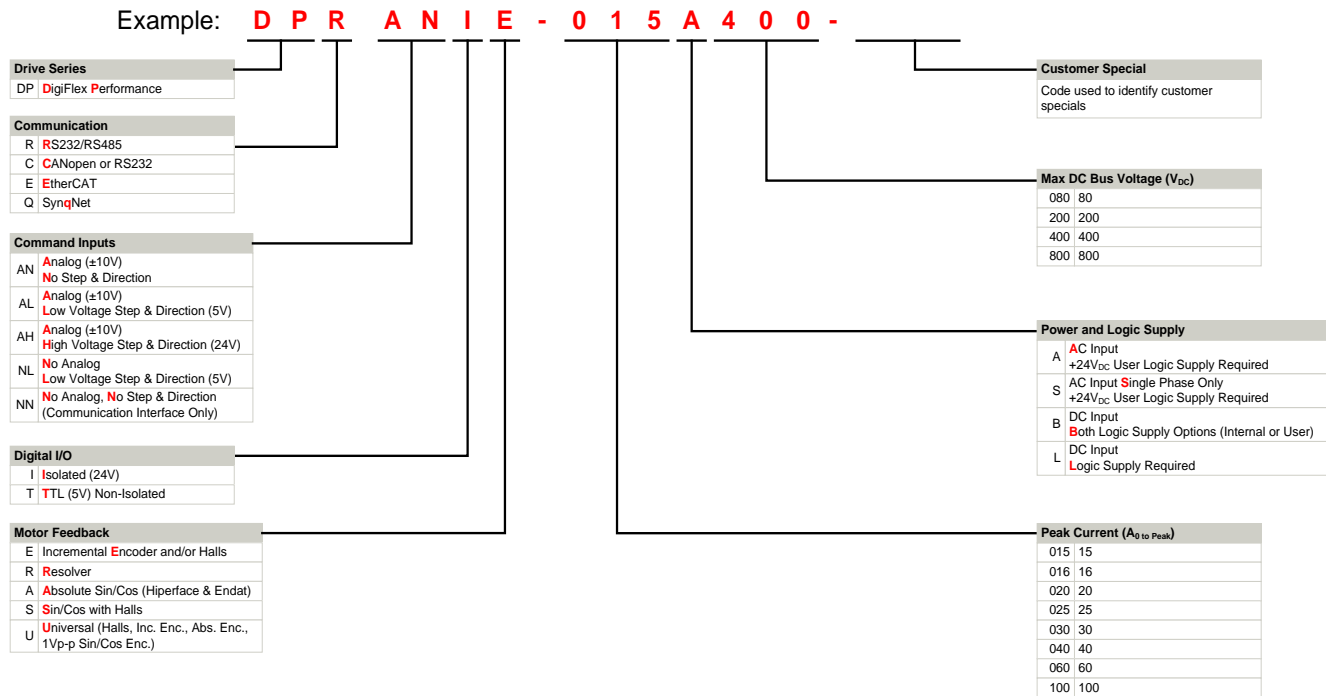


**MOUNTING DIMENSIONS**





**PART NUMBERING INFORMATION**



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

**Examples of Customized Products**

- ▲ Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ▲ Integrated System I/O
- ▲ Tailored Project File
- ▲ Silkscreen Branding
- ▲ Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- ▲ Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

**Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit [www.a-m-c.com](http://www.a-m-c.com) to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.